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(71)Name of Applicant :  
1)Mr.Ankur Jain  
Address of Applicant :Assistant Professor, Department of Computer Science and Engineering, IFTM University, Lodhipur Rajput Delhi Road, Moradabad,Uttar Pradesh,India- 244102 -----  
2)Mr.Ashish Nagila  
3)Mr.Sanjeev Bhardwaj  
4)Mr. Swapnil Uttamrao Deokar  
5)Dr.N.Rajamurugu  
6)Mr .SOMASHEKAR V  
7)Mr.S. GANESH  
8)Dr. Praveen Gupta  
9)Mrs.PVN Rajeswari  
10)Dr. Shivashekharayya V. Viraktamath  
11)Dr .Anup Purushottamrao Bhat  
12)Dr.Gowtham Palanirajan  
Name of Applicant : NA  
Address of Applicant : NA  
(72)Name of Inventor :  
1)Mr.Ankur Jain  
Address of Applicant :Assistant Professor, Department of Computer Science and Engineering, IFTM University, Lodhipur Rajput Delhi Road, Moradabad,Uttar Pradesh,India- 244102 -----  
2)Mr.Ashish Nagila  
Address of Applicant :Assistant Professor, Department of Computer Science and Engineering, IFTM University, Lodhipur Rajput Delhi Road, Moradabad,Uttar Pradesh,India- 244102 -----  
3)Mr.Sanjeev Bhardwaj  
Address of Applicant :Assistant Professor, Department of Computer Science and Engineering, IFTM University, Lodhipur Rajput Delhi Road, Moradabad,Uttar Pradesh,India- 244102 -----  
4)Mr. Swapnil Uttamrao Deokar  
Address of Applicant :Assistant Professor, Department of Mechanical Engineering, Smt. Kashibai Navale College of Engineering, Pune, Survey No 44/1, Sinhgad Road Vadgav Bu Pune-411041, Maharashtra, India. ---  
5)Dr.N.Rajamurugu  
Address of Applicant :Assistant Professor, Department of Aeronautical Engineering, Bharath Institute of Science and Technology, Chennai, Tamilnadu- India, 600073 -----  
6)Mr .SOMASHEKAR V  
Address of Applicant :Assistant professor, Aeronautical Engineering, Acharya Institute of Technology, Acharya Doctor Sarvepalli , Radhakrishna road, Soladevanahalli, 560107 Bengaluru Karnataka India -----  
7)Mr.S. GANESH  
Address of Applicant :Assistant Professor (OG), Department of Mechanical Engineering , SRM Institute of Science and Technology --Ramapuram, Chennai,TAMILNADU,India -----  
8)Dr. Praveen Gupta  
Address of Applicant :Assistant Professor, Department of Computer Science and Engineering., GITAM (Deemed to be University), GandhiNagar, Rushikonda,Visakhapatnam, Andhra Pradesh 530045, Visakhapatnam, Andhra Pradesh- India -----  
9)Mrs.PVN Rajeswari  
Address of Applicant :Associate professor, Department of computer Science and Engineering , PBR VITS, Kavali, Andhra Pradesh, India- 524201 -----  
10)Dr. Shivashekharayya V. Viraktamath  
Address of Applicant :Assistant Professor, Department of E&CE, SDM College of Engineering & Technology, Dharwad, Karnataka, India-580002 -----  
11)Dr .Anup Purushottamrao Bhat  
Address of Applicant :Assistant Professor, Department of Electronic, Amolakchand Mahavidyalaya Yavatmal, Godhani road Yavatmal, Maharashtra- 45001, India. -----  
12)Dr.Gowtham Palanirajan  
Address of Applicant :Associate Professor, Department of Electronics and communication Engineering, Jansons Institute of Technology, Coimbatore,Tamilnadu, India,641659 -----

(57) Abstract :  
The invention pertains to machine vision and intelligent control and describes a monocular vision technique to identify and locate the edge of a road. There are two approaches for detecting the edge of a road that may be used in visual navigation or intelligent control of a robot. These methods target a continuous road with various edge characteristics. The road's margin may be detected using either a color-based approach or a threshold value dividing method according to the invention. It is possible to calculate the perpendicular distance and robot course angle from the robot's current position to the edge of the road using an image that has been inverted perspective projected. This results in an image that appears to be a top view but is a front view, which is then reversed. With its great anti-interference performance, instantaneity, and suitability for both semi-structured and unstructured roadways, this system is simple to apply.

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